

Optical reading head PCV100-F200-B17-V1D-6011-6997

- Non-contact positioning on Data Matrix code tape
- Mechanically rugged: no wearing parts, long operating life, maintenancé-free
- High resolution and precise positioning, especially for facilities with curves and switch points as well as inclines and declines.
- Travel ranges up to 10 km, in X and Y direction
- PROFINET interface
- Integrated switch

Read head for incident light positioning system

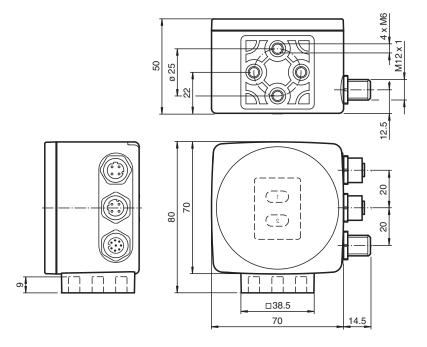








Dimensions



Technical Data

General specifications		
Passage speed	V	≤ 6 m/s
Measuring length		max. 10000 m
Light type		Integrated LED lightning (red)
Scan rate		40 s ⁻¹
Read distance		100 mm
Depth of focus		± 40 mm
Reading field		60 mm x 35 mm
Ambient light limit		100000 Lux
Resolution		± 0.1 mm
Nominal ratings		

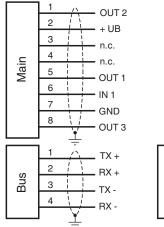
Camera

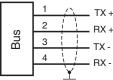
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Technical Data			
Туре		CMOS , Global shutter	
Processor		omoo, aloba onato	
Clock pulse frequency		600 MHz	
Speed of computation		4800 MIPS	
Digital resolution		32 Bit	
Functional safety related parameters		<u></u>	
MTTF _d		99 a	
Mission Time (T _M)		20 a	
Diagnostic Coverage (DC)		0%	
Indicators/operating means			
LED indication		7 LEDs (communication, alignment aid, status information)	
Electrical specifications		(
Operating voltage	U_B	15 30 V DC , PELV	
No-load supply current	I ₀	max. 400 mA	
Power consumption	P ₀	6 W	
Interface	- 0		
Interface type		100 BASE-TX	
Protocol		PROFINET IO Real-Time (RT) Conformance class A	
Transfer rate		100 MBit/s	
Interface 2			
Interface type		USB Service	
Input			
Input type		1 funtion input 0-level: -U _B or unwired 1-level: +8 V +U _B , programmable	
Input impedance		≥ 27 kΩ	
Output			
Output type		1 to 3 switch outputs, programmable, short-circuit protected	
Switching voltage		Operating voltage	
Switching current		150 mA each output	
Conformity		•	
Photobiological safety		exempt group according to EN 62471:2008	
Standard conformity			
Emitted interference		EN 61000-6-4:2007+A1:2011	
Noise immunity		EN 61000-6-2:2005	
Shock resistance		EN 60068-2-27:2009	
Vibration resistance		EN 60068-2-6:2008	
Approvals and certificates			
CE conformity		CE	
UKCA conformity		UKCA	
UL approval		cULus Listed, General Purpose, Class 2 Power Source, Type 1 enclosure	
CCC approval			
Ambient conditions		CCC approval / marking not required for products rated ≤36 V	
Operating temperature		CCC approval / marking not required for products rated ≤36 V	
		CCC approval / marking not required for products rated \le 36 V 0 60 °C (32 140 °F) , -20 60 °C (-4 140 °F) (noncondensing; prevent icing on the lens!)	
Storage temperature		0 60 °C (32 140 °F) , -20 60 °C (-4 140 °F) (noncondensing; prevent icing	
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Storage temperature		0 60 °C (32 140 °F) , -20 60 °C (-4 140 °F) (noncondensing; prevent icing on the lens!) -20 85 °C (-4 185 °F)	
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Technical Data	
Dimensions	
Height	70 mm
Width	70 mm
Depth	50 mm
Factory settings	
X resolution (protocol)	1 mm
Y resolution (protocol)	1 mm
Code tape orientation	0 °
Address	0
"No Position" X value	0
"No Position" Y value	0
"No Position" speed value	127
Overspeed threshold (protocol)	12.5 m/s
X value in case of error	Error number
Y value in case of error	Error number
Speed value in case of error	Error number
Code tape width	two-rowed
X positon offset	0 mm
Function input/output	inactive

Connection





Connection Assignment

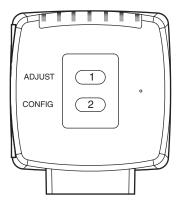
Main

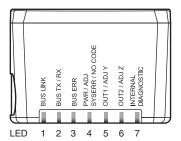


Profinet 1 & 2



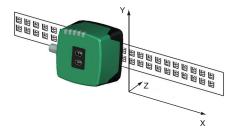
Indication





Characteristic Curve

Coordinates



General

The reading head is part of the positioning system in the method for measurement by Pepperl+Fuchs. It consists of a camera module and an integrated illumination unit among other things. The reading head detects position marks, which are put on an adhesive code band in the form of Data Matrix code. The mounting of the code band is as a rule stationary on a firm part of the plant (elevator shaft, overhead conveyor mounting rails...); that of the reading head is parallel on the moving "vehicle" (elevator car, overhead conveyor chassis...).

Mounting and commissioning

Mount the reading head such that its optical surface captures the optimal read distance to the code band (see Technical Data). The stability of the mounting and the guidance of the vehicle must be provided such that the depth of field of the reading head is not closed during operation. All reading heads can be optimally customized by parameterization for specific requirements.

Displays and Controls

The reading head allows visual function check and fast diagnosis with 7 indicator LEDs. The reading head has 2 buttons on the reverse of the device to activate the alignment aid and parameterization mode.

LEDs

LED	Color	Label	Meaning
1	green	BUS LINK	PROFINET communication active
2	yellow	BUS TX / RX	Data transfer
3	red	BUS ERR	PROFINET communication Error
4	red / green	PWR / ADJ SYSERR / NO CODE	Code recognized / not recognized, Error
5	yellow	OUT1/ADJ Y	Output 1, Alignment aid Y
6	yellow	OUT2/ADJ Z	Output 2, Alignment aid Z
7	red/green/yellow	INTERNAL DIAGNOSTIC	Internal diagnostics

Alignment aid for the Y and Z coordinates

The activation of the alignment aid is only possible within 10 minutes of switching on the reading head. The switchover from normal operation to "alignment aid operating mode is via button 1 on the reverse of the reading head.

- Press the button 1 for longer than 2 s. LED4 flashes green for a recognized code band. LED4 flashes red for an unrecognized code band.
- Z coordinate: If the distance of the camera to the code band too small, the yellow LED6 lights up. If the distance of the camera to the code
 band too large, the yellow LED6 lights up. Within the target range, the yellow LED6 flashes at the same time as the green LED4.
- Y coordinate: If the optical axis of the camera is too deep in relation to the middle of the code band, the yellow LED5 lights up. If the optical axis is too high, the yellow LED5 extinguishes. Within the target range, the yellow LED5 flashes at the same time as the green LED4.
- A short press on button 1 ends the alignment aid and the reading head changes to normal operation.